# AN EXISTENCE RESULT OF WEAK SOLUTIONS TO DIRICHLET PROBLEM FOR NONLINEAR SECOND ORDER SYSTEMS OF DIVERGENCE TYPE 

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#### Abstract

We obtain an existence result for the weak solutions in the Sobolev space $\boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right), p>2$, to the Dirichlet problem for a nonlinear second order system of divergence type. In fact, it is proved that, in certain hypotheses, the operator naturally associated to the Dirichlet problem is a bounded and coercive Gårding operator [10]. We get a generalization of the results obtained in [4] for the Dirichlet problem of nonlinear elastostatics.


Key words: Sobolev spaces; weak solutions; Gårding operator.

## 4. SOME FEW PRELIMINARIES

A. The summation over repeated subscripts is understood and the notation $i=\overline{p, q}$, where $p \leq q$ are integers, means that the index $i$ takes the values $p, p+1, . ., q$.

If $\boldsymbol{a}, \boldsymbol{b} \in \mathbb{R}^{k}$ then $\boldsymbol{a} \cdot \boldsymbol{b}$ is the standard scalar product on $\mathbb{R}^{k}$ and $|\boldsymbol{a}|$ is the corresponding Euclidean norm of $\boldsymbol{a} \cdot \mathbb{M}_{m \times n}$ denotes the linear space of matrices $A=\left(a_{i j}\right)$ of elements $a_{i j} \in \mathbb{R}, i=\overline{1, m}, j=\overline{1, n}$. The application $(A, B) \mapsto \operatorname{tr}\left(A B^{T}\right), \quad A, B \in \mathbb{M}_{m \times n}$, is the standard inner product on $\mathbb{M}_{m \times n}$ and $|A|$ is the corresponding norm of $A$.
B. Throughout this paper we suppose $\Omega \subset \mathbb{R}^{n}$ is a bounded Lipschitz domain ([1], [3], [5], [9]) with boundary $\partial \Omega$, and $\mathrm{d} \boldsymbol{x}$ denotes the Lebesgue measure on $\Omega$.

We use the notation [6] $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right), \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$, and $\boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right), p \in[1, \infty)$, for the Banach spaces of $\mathbb{R}^{m}$-valued functions $u=\left(u_{1}, \ldots, u_{m}\right): \Omega \rightarrow \mathbb{R}^{m}$, with components $u_{k}: \Omega \rightarrow \mathbb{R}, k=\overline{1, m}$, belonging to Banach spaces $L^{p}(\Omega), W^{1, p}(\Omega)$, and $W_{0}^{1, p}(\Omega)$ respectively. $L^{p}\left(\Omega, \mathbb{R}^{m}\right)$ is a Banach space, separable for $p \in[1, \infty)$ and reflexive for $p \in(1, \infty)$, with respect to the norm

$$
\boldsymbol{u} \mapsto\|\boldsymbol{u}\|_{0, p} \equiv\|\boldsymbol{u}\|_{p}:=\left(\int_{\Omega}|\boldsymbol{u}|^{p} \mathrm{~d} \boldsymbol{x}\right)^{1 / p} \in[0, \infty), \quad \boldsymbol{u} \in \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right) .
$$

If $(\boldsymbol{u}, \boldsymbol{v}) \in \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right) \times \boldsymbol{L}^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right), p \in(1, \infty), 1 / p+1 / p^{\prime}=1$, then the function $(\boldsymbol{u} \cdot \boldsymbol{v})(\boldsymbol{x}):=\boldsymbol{u}(\boldsymbol{x}) \cdot \boldsymbol{v}(\boldsymbol{x})$, $x \in \Omega$, belongs to $L^{1}(\Omega)[7]$ and it holds the Hölder inequality

$$
\int_{\Omega} \boldsymbol{u} \cdot \boldsymbol{v} \mathrm{d} \boldsymbol{x} \leq \int_{\Omega}\left|\boldsymbol{u}\|\boldsymbol{v} \mid \mathrm{d} \boldsymbol{x} \leq\| \boldsymbol{u}\left\|_{p}\right\| \boldsymbol{u} \|_{p^{\prime}} .\right.
$$

The dual of $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$ is $\boldsymbol{L}^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$, i.e. $\left(\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)\right)^{\prime}=\boldsymbol{L}^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$, and duality pairing on $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right) \times \boldsymbol{L}^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$ is defined by

$$
\langle u, v\rangle=\int_{\Omega} \boldsymbol{u} \cdot v d \boldsymbol{x} .
$$

The Sobolev space $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ ([1]-[3], [5], [6], [9]) is separable for $p \in[1, \infty)$ and reflexive for $p \in(1, \infty)$, with respect to the norm

$$
\boldsymbol{u} \mapsto\|\boldsymbol{u}\|_{l, p}:=\left\{\int_{\Omega}\left[|\boldsymbol{u}|^{p}+|\nabla \boldsymbol{u}|^{p}\right] d \boldsymbol{x}\right\}^{1 / p}=\left(\|\boldsymbol{u}\|_{p}^{p}+\|\nabla \boldsymbol{u}\|_{p}^{p}\right)^{1 / p} \in[0, \infty) .
$$

Here $\nabla \boldsymbol{u}$ is the distributional gradient of $\boldsymbol{u}$, i.e.

$$
\nabla \boldsymbol{u}=(\nabla \boldsymbol{u})_{i j}: \Omega \rightarrow \mathbb{M}_{m \times n}, \quad(\nabla \boldsymbol{u})_{i j}:=D_{j} u_{i},
$$

$D_{j} u_{i}$ is the $j$-th partial generalized derivative of $u_{i} . W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ is a closed subspace of $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ and, in view of Poincare's inequality ([2], [3], [6]), $\|\boldsymbol{u}\|_{p} \leq k\|\nabla \boldsymbol{u}\|_{p}, \boldsymbol{u} \in W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$, where

$$
\boldsymbol{u} \mapsto\|\nabla \boldsymbol{u}\|_{p}:=\left(\int_{\Omega}|\nabla \boldsymbol{u}|^{p} \mathrm{~d} \boldsymbol{x}\right)^{1 / p} \in[0, \infty), \quad \boldsymbol{u} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right),
$$

is a norm equivalent with the norm $\|\cdot\|_{1, p}$ on $W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$.
In our hypothesis on $\Omega$ we have the completely continuous imbedding ([2], [9])

$$
\begin{equation*}
W^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \subset L^{p}\left(\Omega, \mathbb{R}^{m}\right), \quad p \in(1, \infty), \tag{1.1}
\end{equation*}
$$

and for $p>2$ the following continuous and dense imbeddings

$$
\begin{equation*}
W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \subset \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right) \subset \boldsymbol{L}^{2}\left(\Omega, \mathbb{R}^{m}\right) \subset W^{-1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right), \tag{1.2}
\end{equation*}
$$

where $W^{-1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right):=\left(W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)\right)^{\prime}$. If $p>2$ then $p^{\prime} \in(1,2)$ and therefore

$$
\begin{equation*}
L^{p}\left(\Omega, \mathbb{R}^{m}\right) \subset \boldsymbol{X}\left(\Omega, \mathbb{R}^{m}\right):=\boldsymbol{L}^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right) \cap \boldsymbol{W}^{-1, p}\left(\Omega, \mathbb{R}^{m}\right) \subset \boldsymbol{W}^{-1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right) . \tag{1.3}
\end{equation*}
$$

The weak convergence in $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$, denoted by $\boldsymbol{u}_{n}-\boldsymbol{u}$ in $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$, is defined by $\int_{\Omega} \boldsymbol{u}_{n} \cdot \boldsymbol{u} \mathrm{~d} \boldsymbol{x} \rightarrow \int_{\Omega} \boldsymbol{u} \cdot \boldsymbol{v} \mathrm{d} \boldsymbol{x}, \forall \boldsymbol{v} \in \boldsymbol{L}^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$, while the weak convergence in $\boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$, denoted by $\boldsymbol{u}_{n} \rightharpoonup \boldsymbol{u}$ in $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$, is equivalent with ([5], [6])

$$
\boldsymbol{u}_{n} \rightharpoonup \boldsymbol{u} \text { and } D_{i} \boldsymbol{u}_{n} \rightharpoonup D_{i} \boldsymbol{u}, i=\overline{1, m}, \text { in } \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right),
$$

and implies the strong convergence $\boldsymbol{u}_{n} \rightarrow \boldsymbol{u}$ in $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$ (Rellich Theorem [5]).
The quotient space $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right) / W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ is isomorphic to $W^{1 / p^{\prime}, p}\left(\partial \Omega, \mathbb{R}^{m}\right)$ in the sense of the trace operator ([2], [3], [9]).
C. The divergence operator on the set of mappings $\boldsymbol{S}=\left(S_{i j}\right): \Omega \rightarrow \mathbb{M}_{m \times n}$, with $S_{i j} \in W^{1, p}(\Omega)$ is defined by

$$
\boldsymbol{S} \mapsto \operatorname{div} \boldsymbol{S}: \Omega \rightarrow \mathbb{R}^{m}, \quad(\operatorname{div} \boldsymbol{S})_{i}:=D_{i} S_{i j} \subset L^{p}(\Omega) .
$$

D. Definition 1.1 Let $V=(V,\|\cdot\|)$ and $U=\left(U,\|\cdot\| \|_{U}\right)$, $V \subset U$, be two separable and reflexive Banach spaces. Suppose that $V$ is dense in $U$ and that the imbeding $V \subset U$ is completely continuous [1]. The operator $\Lambda: V \rightarrow V^{\prime}$, where $V^{\prime}$ is the topological dual of $V$, is said to be a Gårding operator [10] if $\Lambda(v)=F(v, v), \forall v \in V$, where the operator $F(\cdot, \cdot): V \times V \rightarrow V^{\prime}$ satisfies the conditions:
(i) For every $w \in V, \quad F(\cdot, w): V \rightarrow V^{\prime}$ is hemicontinuous [8], i.e. the real function $t \mapsto\langle v, F(u+t v, w)\rangle \in \mathbb{R}, t \in \mathbb{R}$, is continuous for every $u, v, w \in V,\langle\cdot, \cdot\rangle$ being the pairing duality on $V \times V^{\prime}$ 。
(ii) There exists a continuous function $\gamma: \mathbb{R}^{+} \times \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}, \mathbb{R}^{+}=[0, \infty)$, satisfying the condition $\lim _{\theta \downarrow 0}\left[\theta^{-1} \gamma(x, \theta y)\right]=0, \quad \forall x, y \in \mathbb{R}^{+}, \quad$ such that $\quad\langle u-v, \Lambda(u)-F(v, u)\rangle \geq-\gamma\left(r,\|u-v\|_{U}\right)$, for every $u, v \in B_{\gamma}(0)=\{w \in V:\|w\|<r\}$.
(iii) If $u_{n} \rightharpoonup u$ in $V$, the conditions

$$
\left\{\begin{array}{l}
\liminf
\end{array}\left\langle u_{n}-u, F\left(v, u_{n}\right)-F(v, u)\right\rangle \geq 0, \quad . \quad \forall u, v, w \in V\right.
$$

hold simoultaneously.
One shows [10] that a bounded Gårding operator is a pseudomonotone operator [8].
Definition 1.2 An operator $\Lambda: V \rightarrow V^{\prime}$ is said to be coercive [8] if

$$
\begin{equation*}
\|v\|^{-1}<v, \Lambda(v)>\rightarrow \infty \text { as }\|v\| \rightarrow \infty \tag{1.4}
\end{equation*}
$$

THEOREM 1.1 ([10]) If $V$ is a reflexive and separable Banach space and $\Lambda: V \rightarrow V^{\prime}$ is a bounded and coercive Gårding operator then $\Lambda$ is surjective, i.e. for every $f \in V^{\prime}$ the operator equation $\Lambda(u)=f$ has at least a solution $u \in V$.

## 2. SECOND ORDER SYSTEMS OF DIVERGENCE TYPE

We consider the following second order system of divergence type [9]

$$
\begin{equation*}
-\operatorname{div} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u})-\boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u})=\boldsymbol{f} \tag{2.1}
\end{equation*}
$$

in the unknown function $\boldsymbol{u}=\left(u_{1}, \ldots, u_{m}\right): \Omega \rightarrow \mathbb{R}^{m}$ from $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right), p>2$, where $\Omega \subset \mathbb{R}^{n}$ is a Lipschitz domain and $\boldsymbol{f}=\left(f_{1}, \ldots, f_{m}\right): \Omega \rightarrow \mathbb{R}^{m}$,

$$
\begin{gather*}
\boldsymbol{x}=\left(x_{1}, \ldots, x_{n}\right) \mapsto \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u})(\boldsymbol{x}):=\boldsymbol{S}(\boldsymbol{x}, \boldsymbol{u}(\boldsymbol{x}), \nabla \boldsymbol{u}(\boldsymbol{x})) \in \mathbb{M}_{m \times n}, \boldsymbol{x} \in \Omega \subset \mathbf{R}^{\mathbf{n}},  \tag{2.2}\\
\boldsymbol{x}=\left(x_{1}, \ldots, x_{\mathbf{n}}\right) \mapsto \boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u}(\boldsymbol{x})):=\boldsymbol{b}(\boldsymbol{x}, \boldsymbol{u}(\boldsymbol{x}), \nabla \boldsymbol{u}(\boldsymbol{x})) \in \mathbb{R}^{m}, \boldsymbol{x} \in \Omega \subset \mathbb{R}^{n}, \tag{2.3}
\end{gather*}
$$

are given functions.
Now we present the restrictions imposed to mappings (2.2) and (2.3) for the solvability of the $\operatorname{system}(2.1)$ in $\boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right), p>2$.
(I) Restrictions on $\boldsymbol{S}(\cdot, \cdot)$. a) For every $(\boldsymbol{p}, \boldsymbol{P}) \in \mathbb{R}^{m} \times \mathbb{M}_{m \times n}$, the mapping $\boldsymbol{S}(\cdot, \boldsymbol{p}, \boldsymbol{P}): \Omega \rightarrow \mathbb{M}_{m \times n}$ is (Lebesgue) measurable, i.e. its real components $S_{i j}(\cdot, \boldsymbol{p}, \boldsymbol{P}): \Omega \rightarrow \mathbb{R}, i=\overline{1, m}, j=\overline{1, n}$ are measurable. b) For almost every (a.e.) $x \in \Omega$ the mapping $\boldsymbol{S}(\boldsymbol{x}, \cdot, \cdot): \mathbb{R}^{m} \times \mathbb{M}_{m \times n} \rightarrow \mathbb{M}_{m \times n}$ is Fréchet continuously differentiable. This implies that for a.e. $\boldsymbol{x} \in \Omega$ there exist the "partial derivatives" of $\boldsymbol{S}$ with respect to $\boldsymbol{p} \in \mathbb{R}^{m}$ and $\boldsymbol{P} \in \mathbb{M}_{m \times n}$, i.e. the linear operator

$$
\left\{\begin{array}{l}
(\boldsymbol{p}, \boldsymbol{P}) \mapsto \frac{\partial \boldsymbol{S}}{\partial \boldsymbol{p}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in L\left(\mathbb{R}^{m}, \mathbb{M}_{m \times n}\right)  \tag{2.4}\\
(\boldsymbol{p}, \boldsymbol{P}) \mapsto \frac{\partial \boldsymbol{S}}{\partial \boldsymbol{P}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in L\left(\mathbb{R}^{m}, \mathbb{M}_{m \times n}\right)
\end{array}\right.
$$

which are continuous on $\mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ and are defined by

$$
\begin{cases}\boldsymbol{q}=\quad\left(q_{i}\right) \mapsto \frac{\partial \boldsymbol{S}}{\partial \boldsymbol{p}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \boldsymbol{q}:=\frac{\partial \boldsymbol{S}}{\partial p_{i}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) q_{i} \in \mathbb{M}_{m \times n}, & \boldsymbol{q} \in \mathbb{R}^{m},  \tag{2.5}\\ \boldsymbol{Q}=\left(Q_{i j}\right) \mapsto \frac{\partial \boldsymbol{S}}{\partial \boldsymbol{P}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \boldsymbol{Q}:=\frac{\partial \boldsymbol{S}}{\partial P_{i j}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) Q_{i j} \in \mathbb{M}_{m \times n}, & \boldsymbol{Q} \in \mathbb{M}_{m \times n} .\end{cases}
$$

In (2.4) $L(U, V)$ denotes the space of linear operators from the linear space $U$ to the linear space $V$. c) For every $(\boldsymbol{p}, \boldsymbol{P}) \in \mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ the mappings

$$
\frac{\partial \boldsymbol{S}}{\partial p_{i}}(\cdot, \boldsymbol{p}, \boldsymbol{P}), \frac{\partial \boldsymbol{S}}{\partial P_{i j}}(\cdot, \boldsymbol{p}, \boldsymbol{P}): \Omega \rightarrow \mathbb{M}_{m \times n}, \quad i=\overline{1, m}, j=\overline{1, n},
$$

are measurable. d) Suppose that for every $(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ and $i=\overline{1, m}, j=\overline{1, n}$, the following growth conditions hold:

$$
\left\{\begin{array}{l}
|\boldsymbol{S}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})| \leq \varphi(\boldsymbol{x})+a^{1}|\boldsymbol{p}|+a^{2}|\boldsymbol{P}|,  \tag{2.6}\\
\left|\frac{\partial \boldsymbol{S}}{\partial p_{i}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})\right| \leq \varphi_{i}(\boldsymbol{x})+a_{i}^{1}|\boldsymbol{p}|+a_{i}^{2}|\boldsymbol{P}|, \\
\left|\frac{\partial \boldsymbol{S}}{\partial P_{i j}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})\right| \leq \varphi_{i j}(\boldsymbol{x})+a_{i j}^{1}|\boldsymbol{p}|+a_{i j}^{2}|\boldsymbol{P}|,
\end{array}\right.
$$

where the real functions $\varphi, \varphi_{i}, \varphi_{i j}$ are from $L^{p}(\Omega)$ and $a^{1}, a^{2} ; a_{i}^{1}, a_{i}^{2} ; a_{i j}^{1}, a_{i j}^{2}$ are positive constants independent of ( $\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}$ ).

Remark 2.1 We notice that the conditions $(\mathbf{I})_{a}$ and $(\mathbf{I})_{b}$ (it is required only the continuity of $\boldsymbol{S}(\boldsymbol{x}, \cdot, \cdot)$ for a.e. $\boldsymbol{x} \in \Omega$ ) shows that (2.2) satisfies the Caratheodory conditions ([9], [11]). If moreover the condition (2.6) holds then the (Nemytsky) operator $\boldsymbol{u} \mapsto \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u})$ is a well defined bounded continuous operator from $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$ into $\boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$ [11]; in particular this operator is bounded and continuous from $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ into $L^{p}\left(\Omega, \mathbb{R}^{m}\right)$.

Remark 2.2 If the mapping (2.2) satisfies all the conditions (I), then

$$
\begin{equation*}
\boldsymbol{u} \mapsto-\operatorname{div} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u}) \tag{2.7}
\end{equation*}
$$

is a well defined continuous operator from $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ into $W^{-1, p}\left(\Omega, \mathbb{R}^{m}\right)$ (see [3], [12]), and taking into account the Green's formula in Sobolev spaces [3] we obtain

$$
\begin{equation*}
\langle\boldsymbol{v},-\operatorname{div} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u})\rangle=\int_{\Omega} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u}) \cdot \nabla \boldsymbol{v d} \boldsymbol{x}, \quad \boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right), \tag{2.8}
\end{equation*}
$$

where $\langle\cdot$,$\rangle is the pairing duality of W^{1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$ and $W^{-1, p}\left(\Omega, \mathbb{R}^{m}\right)$.
We note that if $p>2$ then $\boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \subset W_{0}^{1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$ and therefore we have

$$
\langle\boldsymbol{v},-\operatorname{div} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u})\rangle=\int_{\Omega} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u}) \cdot \nabla \boldsymbol{v} \mathrm{d} \boldsymbol{x}
$$

for every $(\boldsymbol{u}, \boldsymbol{v}) \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \times \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$.
Consequently, if restrictions (I) hold an $p>2$, it results that the operator (2.7) determines in a unique way the bounded and continuous operator [11]

$$
\left\{\begin{array}{cc}
\boldsymbol{u} \mapsto A(\boldsymbol{u}) \in \boldsymbol{W}^{-1, p}\left(\Omega, \mathbb{R}^{m}\right), & \boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)  \tag{2.9}\\
\langle\boldsymbol{v}, A(\boldsymbol{u})\rangle=\int_{\Omega} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u}) \cdot \nabla \boldsymbol{v} \mathrm{d} \boldsymbol{x}, & \boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)
\end{array}\right.
$$

(II) Restrictions on $\boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u})$. a) For every $(\boldsymbol{p}, \boldsymbol{P}) \in \mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ the mapping $\boldsymbol{b}(\cdot, \boldsymbol{p}, \boldsymbol{P}): \Omega \rightarrow \mathbb{R}^{m}$ is measurable, i.e. its real components $b_{i}(\cdot, \boldsymbol{p}, \boldsymbol{P})$ are measurable. b) For a.e. $\boldsymbol{x} \in \Omega$, the mapping

$$
\boldsymbol{b}(\boldsymbol{x}, \cdot, \cdot): \mathbb{R}^{m} \times \mathbb{M}_{m \times n} \rightarrow \mathbb{R}^{m}
$$

is Fréchet continuously differentiable. This implies that for a.e. $x \in \Omega$ there exist the "partial derivatives" of $\boldsymbol{b}$ with respect to $\boldsymbol{p} \in \mathbb{R}^{m}$ and $\boldsymbol{P} \in \mathbb{M}_{m \times n}$

$$
\left\{\begin{align*}
&(\boldsymbol{p}, \boldsymbol{P}) \mapsto \frac{\partial \boldsymbol{b}}{\partial p_{i}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in \boldsymbol{L}\left(\mathbb{R}^{m} \times \mathbb{R}^{m}\right),  \tag{2.10}\\
&(\boldsymbol{p}, \boldsymbol{P}) \mapsto \frac{\partial \boldsymbol{b}}{\partial \boldsymbol{P}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in \boldsymbol{L}\left(\mathbb{M}_{m \times n} \times \mathbb{R}^{m}\right),
\end{align*}\right.
$$

which are continuous on $\mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ and are defined through

$$
\left\{\begin{array}{c}
\boldsymbol{q}=\left(q_{i}\right) \mapsto \frac{\partial \boldsymbol{b}}{\partial \boldsymbol{p}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \boldsymbol{q}:=\frac{\partial \boldsymbol{b}}{\partial p_{i}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) q_{i} \in \mathbb{R}^{m}, \quad \boldsymbol{q} \in \mathbb{R}^{m}  \tag{2.11}\\
\boldsymbol{Q}=\left(Q_{i j}\right)
\end{array} \mapsto \frac{\partial \boldsymbol{b}}{\partial \boldsymbol{P}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \boldsymbol{Q}:=\frac{\partial \boldsymbol{b}}{\partial P_{i j}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) Q_{i j} \in \mathbb{R}^{m}, \boldsymbol{Q} \in \mathbb{M}_{m \times n} .\right.
$$

c) For each $(\boldsymbol{p}, \boldsymbol{P}) \in \mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ the mappings

$$
\frac{\partial \boldsymbol{b}}{\partial p_{i}}(\cdot, \boldsymbol{p}, \boldsymbol{P}): \Omega \rightarrow \mathbb{R}^{m}, \frac{\partial \boldsymbol{b}}{\partial P_{i j}}(\cdot, \boldsymbol{p}, \boldsymbol{P}): \Omega \rightarrow \mathbb{M}_{m \times n}, \quad i=\overline{1, m}, j=\overline{1, n}
$$

are measurable. d) The mapping $\boldsymbol{b}(\cdot, \cdot, \cdot)$ satisfies the growth condition

$$
\begin{equation*}
|\boldsymbol{b}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})| \leq \psi(\boldsymbol{x})+b^{1}|\boldsymbol{p}|^{p-1}+b^{2}|\boldsymbol{P}|^{p-1}, \quad \forall(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{M}_{m \times n} \tag{2.12}
\end{equation*}
$$

where $\psi \in \boldsymbol{L}^{p}(\Omega)$ and $b^{1}>0, b^{2}>0$ are constants independent of $(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})$.
Remark 2.3 The condition (II) ${ }_{a}$ and the continuity of $\boldsymbol{b}(\boldsymbol{x}, \cdot, \cdot)$ for a.e. $\boldsymbol{x} \in \Omega$ shows that the mapping (2.3) satisfies the Caratheodory conditions. If moreover the growth condition (2.12) holds it results that the (Nemytsky) operator

$$
\begin{equation*}
\boldsymbol{u} \mapsto B(\boldsymbol{u}):=\boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u}) \tag{2.13}
\end{equation*}
$$

is a bounded continuous operator from $\boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ into $L^{p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right)$.
Remark 2.4 In consideration of Remark 2.2 it results that if $p>2$ then the operator

$$
\begin{equation*}
\boldsymbol{u} \mapsto-\operatorname{div} \boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u})-\boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u}) \tag{2.14}
\end{equation*}
$$

from $W^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ into $\boldsymbol{X}\left(\Omega, \mathbb{R}^{m}\right)$ is a continuous operator and in view of (1.3) it follows that, for $p>2$, the equation (2.1) makes sense for $\boldsymbol{f} \in \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$.

We point out that the operator (2.14) determines in a unique way the bounded and continuous operator

$$
\left\{\begin{align*}
& \boldsymbol{u} \mapsto \Lambda(\boldsymbol{u}):=A(\boldsymbol{u})-B(\boldsymbol{u}) \in X\left(\Omega, \mathbb{R}^{m}\right), \quad \boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right), p>2  \tag{2.15}\\
&\langle\boldsymbol{v}, \Lambda(\boldsymbol{u})\rangle=\int_{\Omega}[\boldsymbol{S}(\boldsymbol{u}, \nabla \boldsymbol{u}) \cdot \nabla \boldsymbol{v}-\boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u}) \cdot \boldsymbol{v}] \mathrm{d} \boldsymbol{x}, \quad \boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)
\end{align*}\right.
$$

## 3. WEAK SOLUTIONS OF THE DIRICHLET PROBLEM FOR THE SYSTEM (2.1)

In the conditions of the preceding Section we have in view to prove the existence of weak solutions $\boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right), p>2$, of the Dirichlet problem

$$
\left\{\begin{array}{c}
-\operatorname{div} \boldsymbol{S}(\nabla \boldsymbol{u}, \nabla \boldsymbol{u})-\boldsymbol{b}(\boldsymbol{u}, \nabla \boldsymbol{u})=\boldsymbol{f} \text { in } \Omega,  \tag{P}\\
\boldsymbol{u}=\boldsymbol{u}_{0} \text { on } \partial \Omega
\end{array}\right.
$$

where $\boldsymbol{f} \in \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right)$ and $\boldsymbol{u}_{0} \in \boldsymbol{W}^{1 / p^{\prime}, p}\left(\partial \Omega, \mathbb{R}^{m}\right)$.
The function $\boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ is called a weak solution to the problem $(\mathrm{P})$ if $\boldsymbol{u}$ is the solution of the variational problem

$$
\begin{equation*}
\Lambda(\boldsymbol{u})=\boldsymbol{f}, \quad \boldsymbol{u}-\boldsymbol{g} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \tag{VP}
\end{equation*}
$$

where the operator $\Lambda$ is defined by (2.15) and $\boldsymbol{g} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ is a mapping having the trace $\boldsymbol{u}_{0}$ on $\partial \Omega$, $\operatorname{tr} \boldsymbol{g}=\boldsymbol{u}_{0}$ (such a mapping does exist [2], [3], [9]). The variational problem (VP) comes back to the variational problem

$$
\begin{equation*}
\Lambda^{g}(\boldsymbol{u}):=\Lambda(\boldsymbol{g}+\boldsymbol{u})=\boldsymbol{f}, \quad \boldsymbol{u} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \tag{3.1}
\end{equation*}
$$

which is equivalent to the problem of finding $\boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ such that

$$
\left\langle\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})-\boldsymbol{f}\right\rangle:=\int_{\Omega}\{\nabla \boldsymbol{v} \cdot \boldsymbol{S}(\boldsymbol{g}+\boldsymbol{u}, \nabla(\boldsymbol{g}+\boldsymbol{u}))-\boldsymbol{v} \cdot[\boldsymbol{b}(\boldsymbol{g}+\boldsymbol{u}, \nabla(\boldsymbol{g}+\boldsymbol{u}))-\boldsymbol{f}]\} \mathrm{d} \boldsymbol{x}=0
$$

for every $\boldsymbol{v} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$.
Further we are going to use the following
Lemma 3.1 For every $\boldsymbol{g} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ and $\boldsymbol{u}, \boldsymbol{v} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ we have

$$
\begin{equation*}
\left\langle\boldsymbol{u}-\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})-\Lambda^{g}(\boldsymbol{v})\right\rangle=L_{0}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v})+L_{1}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}) \tag{3.2}
\end{equation*}
$$

Where

$$
\left\{\begin{array}{l}
L_{0}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v})=\int_{0}^{1} \mathrm{~d} t \int_{\Omega} \nabla \boldsymbol{h} \cdot\left[\frac{\partial \boldsymbol{S}}{\partial \boldsymbol{p}}(\boldsymbol{g}+\boldsymbol{w}, \nabla(\boldsymbol{g}+\boldsymbol{w})) \boldsymbol{h}+\frac{\partial \boldsymbol{S}}{\partial \boldsymbol{P}}(\boldsymbol{g}+\boldsymbol{w}, \nabla(\boldsymbol{g}+\boldsymbol{w})) \nabla h\right] \mathrm{d} \boldsymbol{x},  \tag{3.3}\\
L_{1}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v})=\int_{0}^{1} \mathrm{~d} t \int_{\Omega}^{\boldsymbol{h}} \cdot\left[\frac{\partial \boldsymbol{b}}{\partial \boldsymbol{p}}(\boldsymbol{g}+\boldsymbol{w}, \nabla(\boldsymbol{g}+\boldsymbol{w})) \boldsymbol{h}+\frac{\partial \boldsymbol{b}}{\partial \boldsymbol{P}}(\boldsymbol{g}+\boldsymbol{w}, \nabla(\boldsymbol{g}+\boldsymbol{w})) \nabla h\right] \mathrm{d} \boldsymbol{x}
\end{array}\right.
$$

and $\boldsymbol{w}=\boldsymbol{v}+t \boldsymbol{h}, \boldsymbol{h}=\boldsymbol{u}-\boldsymbol{v}$.
PROOF: From (2.15) we obtain

$$
\begin{aligned}
\langle\boldsymbol{u}-\boldsymbol{v}, & \left.\Lambda^{g}(\boldsymbol{u})-\Lambda^{g}(\boldsymbol{v})\right\rangle= \\
& =\int_{\Omega} \nabla \boldsymbol{h} \cdot[\boldsymbol{S}(\boldsymbol{g}+\boldsymbol{u}, \nabla(\boldsymbol{g}+\boldsymbol{u}))-\boldsymbol{S}(\boldsymbol{g}+\boldsymbol{v}, \nabla(\boldsymbol{g}+\boldsymbol{v}))] \mathrm{d} \boldsymbol{x}-\int_{\Omega}^{\boldsymbol{h}} \cdot[\boldsymbol{b}(\boldsymbol{g}+\boldsymbol{u}, \nabla(\boldsymbol{g}+\boldsymbol{u}))-\boldsymbol{b}(\boldsymbol{g}+\boldsymbol{v}, \nabla(\boldsymbol{g}+\boldsymbol{v}))] \mathrm{d} \boldsymbol{x}= \\
& =\int_{\Omega}\left[\nabla \boldsymbol{h} \cdot \int_{0}^{1} \frac{\mathrm{~d} \boldsymbol{S}}{\mathrm{~d} t}(\boldsymbol{g}+\boldsymbol{w}, \nabla(\boldsymbol{g}+\boldsymbol{w})) \mathrm{d} t\right] \mathrm{d} \boldsymbol{x}-\int_{\Omega}\left[\boldsymbol{h} \cdot \int_{0}^{1} \frac{\mathrm{~d} \boldsymbol{b}}{\mathrm{~d} t}(\boldsymbol{g}+\boldsymbol{w}, \nabla(\boldsymbol{g}+\boldsymbol{w})) \mathrm{d} t\right] \mathrm{d} \boldsymbol{x}
\end{aligned}
$$

where $\boldsymbol{w}=\boldsymbol{v}+t \boldsymbol{h}, \boldsymbol{h}=\boldsymbol{u}-\boldsymbol{v}$. Taking into account that $\boldsymbol{S}(\boldsymbol{x}, \cdot, \cdot)$ and $\boldsymbol{b}(\boldsymbol{x}, \cdot, \cdot)$ are Fréchet differentiable and applying the Chain Rule we get (3.2).

## 4. AN EXISTENCE RESULT OF THE PROBLEM (P)

THEOREM 4.1 If for every $\boldsymbol{u}, \boldsymbol{h} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ and $(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{M}_{m \times n}$ we have
$\left(\mathbf{H}_{1}\right)$

$$
\left\{\begin{array}{c}
\int_{0}^{1} \mathrm{~d} t \int_{\Omega} \nabla \boldsymbol{h} \cdot \frac{\partial \boldsymbol{S}}{\partial \boldsymbol{P}}(\boldsymbol{u}+t \boldsymbol{h}, \nabla(\boldsymbol{u}+t \boldsymbol{h})) \nabla \boldsymbol{h} \mathrm{d} \boldsymbol{x} \geq c_{0}\|\boldsymbol{h}\|_{1, p}^{p} \\
\int_{0}^{1} \mathrm{~d} t \int_{\Omega} \nabla \boldsymbol{h} \cdot \frac{\partial \boldsymbol{S}}{\partial \boldsymbol{p}}(\boldsymbol{u}+t \boldsymbol{h}, \nabla(\boldsymbol{u}+t \boldsymbol{h})) \boldsymbol{h} \mathrm{d} \boldsymbol{x} \geq 0
\end{array}\right.
$$

and
$\left(\mathbf{H}_{2}\right)$

$$
\left\{\begin{array}{l}
\int_{0}^{1} \mathrm{~d} t \int_{\Omega} \boldsymbol{h} \cdot \frac{\partial \boldsymbol{b}}{\partial \boldsymbol{p}}(\boldsymbol{u}+t \boldsymbol{h}, \nabla(\boldsymbol{u}+t \boldsymbol{h})) \boldsymbol{h} \mathrm{d} \boldsymbol{x} \leq 0 \\
\left|\frac{\partial \boldsymbol{b}}{\partial \boldsymbol{P}}(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})\right| \leq c_{1}\left(1+|\boldsymbol{p}|^{q-1}+|\boldsymbol{P}|^{q-1}\right)
\end{array}\right.
$$

where $q \in(1, p-1)=\left(1, p / p^{\prime}\right)$, and $c_{0}>0, c_{1}>0$ are constants independent of $\boldsymbol{u}, \boldsymbol{h}$ and $(\boldsymbol{x}, \boldsymbol{p}, \boldsymbol{P})$, then the bounded and continuous operator

$$
\begin{cases}\boldsymbol{u} \mapsto \Lambda^{g}(\boldsymbol{u}) \in \boldsymbol{W}^{-1, p}\left(\Omega, \mathbb{R}^{m}\right), & \boldsymbol{u} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right),  \tag{4.1}\\ \left\langle\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})\right\rangle=\int_{\Omega}[\nabla \boldsymbol{v} \cdot \boldsymbol{S}(\boldsymbol{g}+\boldsymbol{u}, \nabla(\boldsymbol{g}+\boldsymbol{u}))-\boldsymbol{v} \cdot \boldsymbol{b}(\boldsymbol{g}+\boldsymbol{u}, \nabla(\boldsymbol{g}+\boldsymbol{u}))] \mathrm{d} \boldsymbol{x}, & \boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right),\end{cases}
$$

is $a$ Gårding coercive operator.
PROOF: A. The operator (4.1) is a Gårding operator. In view of imbeddings (1.1) and (1.2) we can chose $V=W_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ and $U=L^{p}\left(\Omega, \mathbb{R}^{m}\right)$ in Def. 1.1 of Gårding operators. In this definition we take [10]

$$
\begin{equation*}
(\boldsymbol{u}, \boldsymbol{v}) \mapsto F(\boldsymbol{u}, \boldsymbol{v}):=\Lambda^{g}(\boldsymbol{u})+\mathbf{0}(\boldsymbol{v})=\Lambda^{g}(\boldsymbol{u}) \in \boldsymbol{W}^{-1, p^{\prime}}\left(\Omega, \mathbb{R}^{m}\right), \quad \boldsymbol{u}, \boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \tag{4.2}
\end{equation*}
$$

where $\mathbf{0}$ is the null operator. With this choice, the condition (iii) in Def. 1.1 is trivially satisfied because $F\left(\boldsymbol{v}, \boldsymbol{u}_{n}\right)-F(\boldsymbol{v}, \boldsymbol{u})=0$ for every $\boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$. The condition (i) of Def. 1.1 is fulfilled since $F(\boldsymbol{u}+t \boldsymbol{v}, \boldsymbol{w})=\Lambda^{g}(\boldsymbol{u}+t \boldsymbol{v})$ for every $\boldsymbol{u}, \boldsymbol{v}, \boldsymbol{w} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ and $t \in \mathbb{R}$, and the real function

$$
t \mapsto\left\langle\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u}+t \boldsymbol{v})\right\rangle=\int_{\Omega}[\nabla \boldsymbol{v} \cdot \boldsymbol{S}(\boldsymbol{u}+t \boldsymbol{v}, \nabla(\boldsymbol{u}+t \boldsymbol{v}))-\boldsymbol{v} \cdot \boldsymbol{b}(\boldsymbol{u}+t \boldsymbol{v}, \nabla(\boldsymbol{u}+t \boldsymbol{v}))] \mathrm{d} \boldsymbol{x} \in \mathbb{R}, t \in \mathbb{R}
$$

is continuous in consideration of condition $(\mathbf{I})_{b}$ and (II) $)_{b}$. Consequently, to prove that $\Lambda^{g}$ is a Gårding operator we have only to show that, with $F$ given by (4.2), the condition (ii) of Def. 1.1 is verified.

Taking into account $\left(\mathbf{H}_{1}\right)$ and $\left(\mathbf{H}_{2}\right)$ we get

$$
\begin{gather*}
L_{0}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}) \geq c_{0}\|\boldsymbol{u}-\boldsymbol{v}\|_{i, p}^{p}  \tag{4.3}\\
-L_{1}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}) \leq c_{1} \int_{\Omega}|\boldsymbol{h} \| \nabla \boldsymbol{h}| \mathrm{d} \boldsymbol{x} \int_{0}^{1}\left[1+|\boldsymbol{g}+\boldsymbol{w}|^{q-1}+|\nabla \boldsymbol{g}+\nabla \boldsymbol{w}|^{q-1}\right] \mathrm{d} t \leq \\
\leq c_{1} \int_{0}^{1} \mathrm{~d} t \int_{\Omega}|\boldsymbol{h} \| \nabla \boldsymbol{h}|\left\{1+2^{q-1}\left[\left(|\boldsymbol{g}|^{q-1}+|\nabla \boldsymbol{g}|^{q-1}\right)+\left(|\boldsymbol{v}+\boldsymbol{h} \boldsymbol{h}|^{q-1}+|\nabla(\boldsymbol{v}+t \boldsymbol{h})|^{q-1}\right)\right]\right\} d \boldsymbol{x} . \tag{4.4}
\end{gather*}
$$

Using some elementary results from the theory of $L^{p}(\Omega)$ spaces ([1], [2], [7]), taking into account that $p>2$, and $\Omega \subset \mathbb{R}^{n}$ is a bounded Lipschitz domain we obtain: a) Because $\boldsymbol{h} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ it follows that $|\boldsymbol{h}|,|\nabla \boldsymbol{h}| \in L^{p}(\Omega) \subset L^{2}(\Omega)$ and therefore

$$
\begin{equation*}
\int_{\Omega}\left|\boldsymbol{h}\|\nabla \boldsymbol{h} \mid d \boldsymbol{x} \leq\| \boldsymbol{h}\left\|_{2}\right\| \nabla \boldsymbol{h} \|_{2} \leq \text { const. }\|\boldsymbol{h}\|_{p}\|\nabla \boldsymbol{h}\|_{p}\right. \tag{4.5}
\end{equation*}
$$

since $\|\cdot\|_{2} \leq$ const. $\left.\|\cdot\|_{p} . b\right)$ Let us point out the implications:

$$
\begin{gathered}
q \in(1, p-1) \Rightarrow 0<p(q-1) /(p-2)<p \Rightarrow L^{p}(\Omega) \subset L^{s}(\Omega), \quad s=p(q-1) /(p-2), \\
\boldsymbol{g} \in W^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \Rightarrow|\boldsymbol{g}| \in L^{p}(\Omega) \subset L^{s}(\Omega) \Rightarrow|\boldsymbol{g}|^{q-1} \in L^{p /(p-2)}(\Omega) .
\end{gathered}
$$

As $p^{-1}+p^{-1}+\left(\frac{p}{p-2}\right)^{-1}=1$, by virtue of generalized Hölder inequality ([2], [7]), it results that $|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \boldsymbol{g}|^{q-1} \in L^{1}(\Omega)$ and

$$
\int_{\Omega}|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \boldsymbol{g}|^{q-1} d \boldsymbol{x} \leq\|\boldsymbol{h}\|_{p}\|\nabla \boldsymbol{h}\|_{p}\left\|\left.\boldsymbol{g}\right|^{q-1}\right\|_{p /(p-2)}
$$

On the other hand we have $\left|\left\|\left.\boldsymbol{g}\right|^{q-1}\right\|_{p /(p-2)}=\|\boldsymbol{g}\|_{s}^{q-1} \leq\|\boldsymbol{g}\|_{p}^{q-1}\right.$, whereof we obtain

$$
\begin{equation*}
\int_{\Omega}|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \boldsymbol{g}|^{q-1} d \boldsymbol{x} \leq\|\boldsymbol{h}\|_{p}\|\nabla \boldsymbol{h}\|_{p}\left\|\left.\boldsymbol{g}\right|^{q-1}\right\|_{p} \leq \text { const. }\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p} \tag{4.6}
\end{equation*}
$$

c) From the implications $\boldsymbol{g} \in \boldsymbol{W}^{1, p}\left(\Omega, R^{m}\right) \Rightarrow|\nabla \boldsymbol{g}| \in L^{p}(\Omega) \subset L^{s}(\Omega) \Rightarrow \nabla \boldsymbol{g} \mid \in L^{s}(\Omega) \Rightarrow$ $|\nabla \boldsymbol{g}|^{q-1} \in L^{p /(p-2)}(\Omega), \boldsymbol{h} \in W^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \Rightarrow|\boldsymbol{h}|,|\nabla \boldsymbol{h}| \in L^{p}(\Omega)$, and from $p^{-1}+p^{-1}+\left(\frac{p}{p-2}\right)^{-1}=1$ it results that $|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \nabla \boldsymbol{g}|^{q-1} \in L^{1}(\Omega)$ and

$$
\int_{\Omega}|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \nabla \boldsymbol{g}|^{q-1} d \boldsymbol{x} \leq\|\boldsymbol{h}\|_{p}\|\nabla \boldsymbol{h}\|_{p}\|\nabla \boldsymbol{g}\|_{p /(p-2)}
$$

As $\left\|\left\|\left.\boldsymbol{g}\right|^{q-1}\right\|_{p /(p-2)}=\right\| \nabla \boldsymbol{g}\left\|_{s}^{q-1} \leq\right\| \nabla \boldsymbol{g} \|_{p}^{q-1}$ it follows

$$
\begin{equation*}
\int_{\Omega}|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \nabla \boldsymbol{g}|^{q-1} d \boldsymbol{x} \leq\|\boldsymbol{h}\|_{p}\|\nabla \boldsymbol{h}\|_{p}\|\nabla \boldsymbol{g}\|_{p} \leq \text { const. }\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p} \tag{4.7}
\end{equation*}
$$

d) Similarly with (4.6) and (4.7) we obtain

$$
\begin{gather*}
\int_{\Omega} \mid \boldsymbol{h}\|\nabla \boldsymbol{h}\| \boldsymbol{v}+\text { th }\left.\right|^{q-1} d \boldsymbol{x} \leq \text { const. }\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p} \| \boldsymbol{v}+\text { th } \|_{p}^{q-1},  \tag{4.8}\\
\int_{\Omega}|\boldsymbol{h}\|\nabla \boldsymbol{h}\| \nabla(\boldsymbol{v}+t \boldsymbol{h})|^{q-1} d \boldsymbol{x} \leq \mathrm{const} .\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p} \| \nabla(\boldsymbol{v}+\text { th }) \|_{p}^{q-1} . \tag{4.9}
\end{gather*}
$$

From (4.4) $)_{2}$ and (4.5)-(4.9) we have

$$
\begin{equation*}
-L_{1}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}) \leq \text { const. }\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p}\left(1+\|\boldsymbol{v}+\theta \boldsymbol{h}\|_{p}^{q-1}+\|\nabla(\boldsymbol{v}+\theta \boldsymbol{h})\|_{p}^{q-1}\right), \tag{4.10}
\end{equation*}
$$

and, on the other hand

$$
\left\{\begin{array}{l}
\|\boldsymbol{v}+\theta \boldsymbol{h}\|_{p} \leq\|\boldsymbol{v}+\theta \boldsymbol{h}\|_{1, p} \leq\|\boldsymbol{u}\|_{1, p}+2\|\boldsymbol{v}\|_{1, p},  \tag{4.11}\\
\|\nabla(\boldsymbol{v}+\theta \boldsymbol{h})\|_{p} \leq\|\boldsymbol{v}+\theta \boldsymbol{h}\|_{1, p} \leq\|\boldsymbol{u}\|_{1, p}+2\|\boldsymbol{v}\|_{1, p},
\end{array} \quad \theta \in(0,1) .\right.
$$

In view of the dense imbedding (1.2) and (4.11) we have

$$
\begin{equation*}
\|\boldsymbol{v}+\theta \boldsymbol{h}\|_{p}^{q-1} \leq \text { const. } r^{q-1}, \quad\|\nabla(\boldsymbol{v}+\theta \boldsymbol{h})\|_{p}^{q-1} \leq \text { const. } r^{q-1}, \tag{4.12}
\end{equation*}
$$

for every $\boldsymbol{u}, \boldsymbol{v} \in B_{r}(\mathbf{0})=\left\{\boldsymbol{u} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right):\|\boldsymbol{u}\|_{1, p}<r\right\}$. From (4.10) and (4.12) it results

$$
\begin{equation*}
-L_{1}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}) \leq\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p}\left(a_{1}+a_{2} r^{q-1}\right), \quad \boldsymbol{h}=\boldsymbol{u}-\boldsymbol{v}, \boldsymbol{u}, \boldsymbol{v} \in B_{r}(\mathbf{0}) \tag{4.13}
\end{equation*}
$$

where $a_{1}>0$ and $a_{2}>0$ are constants depending on $\Omega, p$, and $\boldsymbol{g}$. By using a variant of the Young inequality [2] we get

$$
\left\{\begin{array}{c}
\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p} \leq \varepsilon\|\boldsymbol{h}\|_{1, p}^{p}+c(\varepsilon)\|\boldsymbol{h}\|_{p}^{p^{\prime}},  \tag{4.14}\\
\|\boldsymbol{h}\|_{p}\|\boldsymbol{h}\|_{1, p} r^{q-1} \leq \varepsilon\|\boldsymbol{h}\|_{1, p}^{p}+c(\varepsilon)\|\boldsymbol{h}\|_{p}^{p^{\prime}} r^{(q-1) p^{\prime}},
\end{array}\right.
$$

where $\varepsilon>0$ is an arbitrary constant, $c(\varepsilon)=\varepsilon^{-1 /(p-1)}$, and $\boldsymbol{h}=\boldsymbol{u}-\boldsymbol{v}$. Therefore, from (4.13), (4.14) we have

$$
\begin{equation*}
-L_{1}(\boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}) \leq\left(a_{1}+a_{2}\right) \varepsilon\|\boldsymbol{h}\|_{1, p}^{p}+\left(a_{1}+a_{2} r^{(q-1) p^{\prime}}\right) c(\varepsilon)\|\boldsymbol{h}\|_{p}^{p^{\prime}}, \tag{4.15}
\end{equation*}
$$

whereof, in view of (4.3), from (3.2) it results

$$
\left\langle\boldsymbol{u}-\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})-\Lambda^{g}(\boldsymbol{v})\right\rangle \geq c_{0}\|\boldsymbol{h}\|_{1, p}^{p}-\left(a_{1}+a_{2}\right) \varepsilon\|\boldsymbol{h}\|_{1, p}^{p}-\left(a_{1}+a_{2} r^{(q-1) p^{\prime}}\right) c(\varepsilon)\|\boldsymbol{h}\|_{p}^{p^{\prime}} .
$$

If in this inequality we take $\varepsilon>0$ sufficiently small, it follows that for every $\boldsymbol{u}, \boldsymbol{v} \in B_{r}(\mathbf{0})$ we have

$$
\begin{equation*}
\left\langle\boldsymbol{u}-\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})-\Lambda^{g}(\boldsymbol{v})\right\rangle \geq b_{0}\|\boldsymbol{u}-\boldsymbol{v}\|_{1, p}^{p}-\left(b_{1}+b_{2} r^{(q-1) p^{\prime}}\right)\|\boldsymbol{u}-\boldsymbol{v}\|_{p}^{p^{\prime}}, \tag{4.16}
\end{equation*}
$$

where $b_{0}>0, b_{1}>0$, and $b_{2}>0$ are constant. Thus we proved that $\Lambda^{g}$ is a Gårding operator for every $\boldsymbol{g} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ since (4.16) implies

$$
\begin{equation*}
\left\langle\boldsymbol{u}-\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})-\Lambda^{g}(\boldsymbol{v})\right\rangle \geq-\gamma\left(r,\|\boldsymbol{u}-\boldsymbol{v}\|_{p}\right), \quad \boldsymbol{u}, \boldsymbol{v} \in B_{r}(\mathbf{0}) \tag{4.17}
\end{equation*}
$$

where $\gamma(x, y)=\left(b_{1}+b_{2} x^{(q-1) p^{\prime}}\right) y^{p^{\prime}}, x \geq 0, y \geq 0$, satisfies $\lim _{\theta \downarrow 0} \theta^{-1} \gamma(x, \theta y)=0, \forall x, y>0$.
B. The operator (4.1) is coercive. By taking $v=0$ in (3.2) we obtain

$$
\begin{equation*}
\left\langle\boldsymbol{u}, \Lambda^{g}(\boldsymbol{u})\right\rangle=L_{0}(\boldsymbol{g}, \boldsymbol{u}, \mathbf{0})+L_{1}(\boldsymbol{g}, \boldsymbol{u}, \mathbf{0})+\left\langle\boldsymbol{u}, \Lambda^{g}(\mathbf{0})\right\rangle \tag{4.18}
\end{equation*}
$$

From (3.3) with $\boldsymbol{v}=0$ and hypotheses $\left(\mathbf{H}_{1}\right),\left(\mathbf{H}_{2}\right)$ we obtain

$$
\left\{\begin{array}{l}
L_{0}(\boldsymbol{g}, \boldsymbol{u}, \mathbf{0}) \geq c_{0}\|\boldsymbol{u}\|_{1, p}^{p}  \tag{4.19}\\
-L_{1}(\boldsymbol{g}, \boldsymbol{u}, \mathbf{0}) \leq \int_{0}^{1} d t \int_{\Omega}|\boldsymbol{u} \| \nabla \boldsymbol{u}|\left\{1+2^{q-1}\left[|\boldsymbol{g}|^{q-1}+|\nabla \boldsymbol{g}|^{q-1}+t^{q-1}\left(|\boldsymbol{u}|^{q-1}+|\nabla \boldsymbol{u}|^{q-1}\right)\right]\right\} d \boldsymbol{x} .
\end{array}\right.
$$

If in estimations (4.5)-(4.9) we take $\boldsymbol{v}=0$ and use the Young inequality as in (4.4) we obtain

$$
\begin{equation*}
-L_{1}(\boldsymbol{g}, \boldsymbol{u}, \mathbf{0}) \leq A_{1} \varepsilon\|\boldsymbol{u}\|_{1, p}^{p^{\prime}}+A_{2} c(\varepsilon)\|\boldsymbol{u}\|_{1, p}^{p^{\prime}}+A_{3} c(\varepsilon)\|\boldsymbol{u}\|_{1, p}^{q p^{\prime}} \tag{4.20}
\end{equation*}
$$

where $A_{1}>0, A_{2}>0, A_{3}>0$ are constants depending on $\Omega, q, \boldsymbol{g}$, and $\varepsilon>0$ is an arbitrary constant.
Applying succesively Hölder and Young inequalities we have

$$
\begin{gather*}
\left|<\boldsymbol{u}, \Lambda^{g}(\mathbf{0})>\right| \leq\|\boldsymbol{S}(\boldsymbol{g}, \nabla \boldsymbol{g})\|_{p^{\prime}}\|\nabla \boldsymbol{u}\|_{p}+\|\boldsymbol{b}(\boldsymbol{g}, \nabla \boldsymbol{g})\|_{p^{\prime}}\|\boldsymbol{u}\|_{p} \leq \\
\leq \varepsilon_{0}\left[\|\boldsymbol{S}(\boldsymbol{g}, \nabla \boldsymbol{g})\|_{p^{\prime}}^{p}+\|\boldsymbol{b}(\boldsymbol{g}, \nabla \boldsymbol{g})\|_{p^{\prime}}^{p}\right]+c\left(\varepsilon_{0}\right)\left[\|\boldsymbol{u}\|_{p}^{p^{\prime}}+\|\nabla \boldsymbol{u}\|_{p}^{p^{\prime}}\right] \leq  \tag{4.21}\\
\leq B_{1}+B_{2}\|\boldsymbol{u}\|_{1, p}^{p^{\prime}},
\end{gather*}
$$

where $B_{1}>0$ and $B_{2}>0$ are constants with evident dependence on $\boldsymbol{S}$ and $\boldsymbol{b}$. From (4.18)-(4.21) we obtain

$$
\begin{equation*}
\left\langle\boldsymbol{u}, \Lambda^{g}(\boldsymbol{u})\right\rangle \geq\left(c_{0}-A_{1} \varepsilon\right)\|\boldsymbol{u}\|_{1, p}^{p}-\left(A_{2} c(\varepsilon)+B_{2}\right)\|\boldsymbol{u}\|_{1, p}^{p^{\prime}}-A_{3} c(\varepsilon)\|\boldsymbol{u}\|_{1, p}^{q p^{\prime}}-B_{1} \tag{4.22}
\end{equation*}
$$

where $\mathcal{E}>0$ is an arbitrary constant. If we take $\varepsilon>0$ sufficiently small in (4.22) it results

$$
\begin{equation*}
\left\langle\boldsymbol{u}, \Lambda^{g}(\boldsymbol{u})\right\rangle \geq C_{0}\|\boldsymbol{u}\|_{1, p}^{p}-C_{1}\|\boldsymbol{u}\|_{1, p}^{p^{\prime}}-C_{2}\|\boldsymbol{u}\|_{1, p}^{q p^{\prime}}-B_{1}, \tag{4.23}
\end{equation*}
$$

from where we get

$$
\begin{equation*}
\|\boldsymbol{u}\|_{1, p}^{-1}\left\langle\boldsymbol{u}, \Lambda^{g}(\boldsymbol{u})\right\rangle \geq\|\boldsymbol{u}\|_{1, p}^{p-1}\left[C_{0}-C_{1}\|\boldsymbol{u}\|_{1, p}^{p^{\prime}-p}-C_{2}\|\boldsymbol{u}\|_{1, p}^{q p^{\prime}-p}-B_{1}\|\boldsymbol{u}\|_{1, p}^{-p}\right] \tag{4.24}
\end{equation*}
$$

for every $\boldsymbol{u} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$. Since $p-1>1, p^{\prime}-p<0$, and $q p^{\prime}<p$ we obtain

$$
\|\boldsymbol{u}\|_{1, p}^{-1}\left\langle\boldsymbol{u}, \Lambda^{g}(\boldsymbol{u})\right\rangle \rightarrow \infty \text { as }\|\boldsymbol{u}\|_{1, p} \rightarrow \infty, \quad \boldsymbol{u} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)
$$

and the theorem is proved (see (1.4)).
Remark 4.1 Because a bounded Gårding operator is pseudomonotone [11], it follows the implication [8]

$$
\left.\begin{array}{c}
\boldsymbol{u}_{n} \rightharpoonup \boldsymbol{u} \text { in } \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right) \\
\text { and } \\
\underset{n \rightarrow \infty}{\limsup }\left\langle\boldsymbol{u}_{n}-\boldsymbol{u}, \Lambda^{g}\left(\boldsymbol{u}_{n}\right)\right\rangle \leq 0
\end{array}\right\} \Rightarrow \liminf _{n \rightarrow \infty}\left\langle\boldsymbol{u}_{n}-\boldsymbol{v}, \Lambda^{g}\left(\boldsymbol{u}_{n}\right)\right\rangle \geq\left\langle\boldsymbol{u}-\boldsymbol{v}, \Lambda^{g}(\boldsymbol{u})\right\rangle
$$

for every $\boldsymbol{v} \in \boldsymbol{W}_{0}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$.
From theorems 1.1 and 4.1 we obtain the desired existence result.

THEOREM 4.2 If $\Omega \subset \mathbb{R}^{n}$ is a Lipschitz bounded domain, $p>2$, and the mappings (2.2) and (2.3) satisfy the restrictions (I) and (II) of Section 2 and the hypotheses $\left(\mathbf{H}_{1}\right)$ and $\left(\mathbf{H}_{2}\right)$ in theorem 4.1 then, for every pair $\left(\boldsymbol{f}, \boldsymbol{u}_{0}\right) \in \boldsymbol{L}^{p}\left(\Omega, \mathbb{R}^{m}\right) \times \boldsymbol{W}^{1 / p^{\prime}, p}\left(\partial \Omega, \mathbb{R}^{m}\right)$, there exists at least one weak solution $\boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$ of the problem $(P)$.

Remark 4.2 From the proof of lemma 3.1 and hypothesis $\left(\mathbf{H}_{1}\right)_{1}$ it results that the operator

$$
\boldsymbol{u} \mapsto A^{g}(\boldsymbol{u}):=A(\boldsymbol{g}+\boldsymbol{u}) \in \boldsymbol{W}^{-1, p}\left(\Omega, \mathbb{R}^{m}\right), \quad \boldsymbol{u} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)
$$

defined by (2.9), is a p-coercive, and consequently a strongly monotone operator ([9]) for every $\boldsymbol{g} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)$, i.e.

$$
\left\langle\boldsymbol{u}-\boldsymbol{v}, A^{g}(\boldsymbol{u})-A^{g}(\boldsymbol{v})\right\rangle \geq c_{0}\|\boldsymbol{u}-\boldsymbol{v}\|_{1, p}^{p}, \quad c_{0}>0, \forall \boldsymbol{u}, \boldsymbol{v} \in \boldsymbol{W}^{1, p}\left(\Omega, \mathbb{R}^{m}\right)
$$

Remark 4.3 If the mapping (2.2) is independent of $\boldsymbol{u}$ and $m=n \geq 1$ then the system (2.1) is a quasilinear differential system of finite n-dimensional elastostatics type. In [4] we obtained some existence results of the weak solutions to the Dirichlet problem for such a system in three dimensions.

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